# **Lecture 16: Bayesian Variable Selection and Model Averaging**

STA702

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[https://sta702-F23.github.io/website/](https://sta702-f23.github.io/website/)

## **Normal Regression Model**

Centered regression model where  $\mathbf{X}^c$  is the  $n \times p$  centered design matrix where all variables have had their means subtracted (may or may not need to be standardized)

$$
\mathbf{Y} = \mathbf{1}_n \alpha + \mathbf{X}^c \boldsymbol{\beta} + \boldsymbol{\epsilon}
$$

- "Redundant" variables lead to unstable estimates
- $\bullet \,\,$  Some variables may not be relevant at all ( $\beta_j = 0$ )
- We want to reduce the dimension of the predictor space
- How can we infer a "good" model that uses a subset of predictors from the data?
- Expand model hierarchically to introduce another latent variable that encodes *γ*  $\mathsf{models}\ \mathcal{M}_\gamma\,\boldsymbol{\gamma}=(\gamma_1,\gamma_2,\dots \gamma_p)^T$  where

$$
\begin{aligned} \gamma_j = 0 &\Leftrightarrow \beta_j = 0 \\ \gamma_j = 1 &\Leftrightarrow \beta_j \neq 0 \end{aligned}
$$

 $\bullet~$  Find Bayes factors and posterior probabilities of models  $\mathcal{M}_\gamma$ 

#### **Priors**

With  $2^p$  models, subjective priors for  $\boldsymbol{\beta}$  are out of the question for moderate  $p$  and improper priors lead to arbitrary Bayes factors leading to **conventional priors** on model specific parameters

Zellner's g-prior and related have attractive properties as a starting point

$$
\boldsymbol{\beta}_{\gamma} \mid \alpha, \phi, \boldsymbol{\gamma} \sim \mathsf{N}(0, g\phi^{-1}(\mathbf{X}^{c}_{\boldsymbol{\gamma}}'\mathbf{X}^{c}_{\boldsymbol{\gamma}})^{-1})
$$

- Independent Jeffrey's prior on common parameters  $(\alpha, \phi)$  $p(\alpha, \phi) \propto 1/\phi$
- marginal likelihood of *γ* that is proportional to

$$
p(\mathbf{Y} \mid \boldsymbol{\gamma}) = C(1+g)^{\frac{n-p_{\boldsymbol{\gamma}-1}}{2}}(1+g(1-R_{\boldsymbol{\gamma}}^2))^{-\frac{(n-1)}{2}}
$$

- $R_\gamma^2$  is the usual coefficient of determination for model  $\mathcal{M}_\gamma.$
- $\boldsymbol{C}$  is a constant common to all models (proportional to the marginal likelihood of the null model where  $\boldsymbol{\beta}_{\boldsymbol \gamma} = \boldsymbol 0_p$

#### **Sketch for Marginal**

- Integrate out  $\beta_{\gamma}$  using sums of normals
- Find inverse of  $\mathbf{I}_n + g \mathbf{P}_{\mathbf{X}_\gamma}$  (properties of projections or Sherman-Woodbury-Morrison Theorem)
- $\bullet$  Find determinant of  $\phi(\mathbf{I}_n+ g \mathbf{P}_{\mathbf{X}_{\gamma}})$
- Integrate out intercept (normal)
- Integrate out  $\phi$  (gamma)
- algebra to simplify quadratic forms to  $R^2_{\boldsymbol\gamma}$

Or integrate  $\alpha$ ,  $\beta_{\gamma}$  and  $\phi$  (complete the square!)

#### **Posterior Distributions on Parameters**

$$
\alpha \mid \gamma, \phi, y \sim \mathsf{N}\left(\bar{y}, \frac{1}{n\phi}\right)
$$
\n
$$
\beta_{\gamma} \mid \gamma, \phi, g, y \sim \mathsf{N}\left(\frac{g}{1+g}\hat{\beta}_{\gamma}, \frac{g}{1+g}\frac{1}{\phi}\left[\mathbf{X}_{\gamma}^{\ T}\mathbf{X}_{\gamma}\right]^{-1}\right)
$$
\n
$$
\phi \mid \gamma, y \sim \text{Gamma}\left(\frac{n-1}{2}, \frac{\text{TotalSS} - \frac{g}{1+g}\text{RegSS}}{2}\right)
$$
\n
$$
\text{TotalSS} \equiv \sum_{i} (y_{i} - \bar{y})^{2}
$$
\n
$$
\text{RegSS} \equiv \hat{\beta}_{\gamma}^{T}\mathbf{X}_{\gamma}^{T}\mathbf{X}_{\gamma}\hat{\beta}\gamma
$$
\n
$$
R_{\gamma}^{2} = \frac{\text{RegSS}}{\text{TotalSS}} = 1 - \frac{\text{ErrorSS}}{\text{TotalSS}}
$$

#### **Priors on Model Space**  $p(\mathcal{M}_\gamma) \Leftrightarrow p(\boldsymbol{\gamma})$

- Fixed prior probability  $\gamma_j \, p(\gamma_j=1) = .5 \Rightarrow P(\mathcal{M}_\gamma) = .5^p$
- Uniform on space of models *p<sup>γ</sup>* ∼ Bin(*p*, .5)
- Hierarchical prior

$$
\gamma_j \mid \pi \stackrel{\text{iid}}{\sim} \text{Ber}(\pi)\\ \pi \sim \text{Beta}(a,b)\\ \text{then } p_{\bm{\gamma}} \sim \text{BB}_p(a,b)
$$

$$
p(p_{\bm{\gamma}} \mid p, a, b) = \frac{\Gamma(p+1)\Gamma(p_{\bm{\gamma}} + a)\Gamma(p - p_{\bm{\gamma}} + b)\Gamma(a + b)}{\Gamma(p_{\bm{\gamma}} + 1)\Gamma(p - p_{\bm{\gamma}} + 1)\Gamma(p + a + b)\Gamma(a)\Gamma(b)}
$$

- Uniform on Model Size ⇒ *p<sup>γ</sup>* ∼ BB*p*(1, 1) ∼ Unif(0, *p*)

#### **Posterior Probabilities of Models**

Calculate posterior distribution analytically under enumeration.

$$
p({\cal M}_\gamma \mid \mathbf{Y}) = \frac{p(\mathbf{Y} \mid \boldsymbol{\gamma})p(\boldsymbol{\gamma})}{\sum_{\boldsymbol{\gamma}' \in \Gamma} p(\mathbf{Y} \mid \boldsymbol{\gamma}')p(\boldsymbol{\gamma}') }
$$

- Express as a function of Bayes factors and prior odds!
- Use MCMC over  $\Gamma$  Gibbs, Metropolis Hastings if  $p$  is large (depends on Bayes factors and prior odds)
- slow convergence/poor mixing with high correlations
- Metropolis Hastings algorithms more flexibility (swap pairs of variables)

No need to run MCMC over  $\gamma$ ,  $\beta_{\gamma}$ ,  $\alpha$ , and  $\phi$ !

### **Choice of g: Bartlett's Paradox**

The Bayes factor for comparing  $\boldsymbol{\gamma}$  to the null model:

$$
BF(\bm{\gamma}:\bm{\gamma}_0)=(1+g)^{(n-1-p_{\bm{\gamma}})/2}(1+g(1-R_{\bm{\gamma}}^2))^{-(n-1)/2}
$$

- For fixed sample size  $n$  and  $R^2_{\boldsymbol\gamma}$ , consider taking values of  $g$  that go to infinity
- Increasing vagueness in prior  $\bullet$
- What happens to BF as  $g \to \infty$ ?

**Bartlett Paradox**

Why is this a paradox?

#### **Information Paradox**

The Bayes factor for comparing *γ* to the null model:

$$
BF(\boldsymbol{\gamma}:\boldsymbol{\gamma}_0)=(1+g)^{(n-1-p_{\boldsymbol{\gamma}})/2}(1+g(1-R_{\boldsymbol{\gamma}}^2))^{-(n-1)/2}
$$

- Let *g* be a fixed constant and take *n* fixed.
- Usual F statistic for testing  $\boldsymbol \gamma$  versus  $\boldsymbol \gamma_0$  is  $F = \frac{R_\gamma^2/p_\gamma}{(1-R^2)/(p_T)}$  $(1-R_\boldsymbol{\gamma}^2)/(n{-}1{-}p_\boldsymbol{\gamma})$
- As  $R^2_{\bm{\gamma}} \to 1$ ,  $F \to \infty$  Likelihood Rqtio test (F-test) would reject  $\bm{\gamma}_0$  where  $F$  is the usual  $F$  statistic for comparing model  $\boldsymbol \gamma$  to  $\boldsymbol \gamma_0$
- $\bullet \,\,$  BF converges to a fixed constant  $(1+g)^{n-1-p_{\gamma}/2}$  (does not go to infinity !

**Information Inconsistency** of [Liang et al JASA 2008](https://www.jstor.org/stable/27640050)

## **Mixtures of g-priors & Information consistency**

- Want  $\mathsf{BF} \to \infty$  if  $\mathsf{R}^2_{\boldsymbol\gamma} \to 1$  if model is full rank
- Put a prior on *g*

$$
BF(\bm{\gamma}:\bm{\gamma}_0)=\frac{C\int (1+g)^{(n-1-p_{\bm{\gamma}})/2}(1+g(1-R_{\bm{\gamma}}^2))^{-(n-1)/2}\pi(g)dg}{C}
$$

interchange limit and integration as  $R^2 \rightarrow 1$  want

$$
{\mathsf E}_g[(1+g)^{(n-1-p_\gamma)/2}]
$$

to diverge under the prior

## **One Solution**

• hyper-g prior (Liang et al JASA 2008)

$$
p(g)=\frac{a-2}{2}(1+g)^{-a/2}
$$

 $\log g/(1+g) \sim Beta(1,(a-2)/2)$  for  $a>2$ 

- prior expectation converges if  $a > n+1-p_{\boldsymbol{\gamma}}$  (properties of  $_2F_1$  function)
- Consider minimal model  $p_{\boldsymbol \gamma} = 1$  and  $n = 3$  (can estimate intercept, one coefficient, and  $\sigma^2$ , then for  $a>3$  integral exists
- For  $2 < a \leq 3$  integral diverges and resolves the information paradox! (see proof in [Liang et al JASA 2008](https://www.jstor.org/stable/27640050))

#### **Examples of Priors on** *g*

- hyper-g prior (Liang et al JASA 2008)
	- **S** Special case is Jeffreys prior for *g* which corresponds to  $a = 2$  (improper)
- Zellner-Siow Cauchy prior 1/*g* ∼ Gamma(1/2, *n*/2)
- Hyper-g/n (*g*/*n*)(1 + *g*/*n*) ∼ Beta(1,(*a* − 2)/2) (generalized Beta distribution)
- robust prior (Bayarri et al Annals of Statistics 2012)
- Intrinsic prior (Womack et al JASA 2015)

All have prior tails for  $\boldsymbol{\beta}$  that behave like a Cauchy distribution and all except the Gamma prior have marginal likelihoods that can be computed using special hypergeometric functions ( $\displaystyle _2F_1$ , Appell  $F_1$ )

No fixed value of *g* (i.e a point mass prior) will resolve!

#### **US Air Example**

```
1 library(BAS)
2 data(usair, package="HH")
3 poll.bma = bas.lm(log(SO2) ~ temp + log(mfgfirms) +
4 log(popn) + wind +
5 precip + raindays,
6 data=usair,
7 prior="JZS", #Jeffrey-Zellner-Siow
8 alpha=nrow(usair), \# n
9 n.models=2^6,
10 modelprior = uniform(),
11 method="deterministic")
```
#### **Summary**

[1](#page-13-0) summary(poll.bma, n.models=4)

<span id="page-13-0"></span>

#### **Plots of Coefficients**

<span id="page-14-0"></span>[1](#page-14-0) beta =  $\text{coef}(\text{poll.bma})$ 

<span id="page-14-1"></span>[2](#page-14-1)  $par(mfrow=c(2,3))$ ;  $plot(beta, subset=2:7, ask=F)$ 



#### **Posterior Distribution with Uniform Prior on Model Space**

<span id="page-15-0"></span>[1](#page-15-0) image(poll.bma, rotate=FALSE)



Log Posterior Odds

http://localhost:4839/resources/slides/16-bma.html?print-pdf=#/summary-1 Page 16 of 19

#### **Posterior Distribution with BB(1,1) Prior on Model Space**

```
1 poll.bb.bma = bas.lm(log(SO2) ~ temp + log(mfgfirms) +
2 log(popn) + wind +
3 precip + raindays,
4 data=usair,
5 prior="JZS",
6 alpha=nrow(usair),
7 n.models=2^6, #enumerate
8 modelprior=beta.binomial(1,1))
```
#### **Posterior Distribution with BB(1,1) Prior on Model Space**



<span id="page-17-0"></span>[1](#page-17-0) image(poll.bb.bma, rotate=FALSE)

Log Posterior Odds

#### **Summary**

- Choice of prior on  $β_γ$
- $\bullet$  g-priors or mixtures of  $g$  (sensitivity)
- priors on the models (sensitivity)
- posterior summaries select a model or "average" over all models